### **Pulsed Laser Drilling**

#### Laser drilling modelling

**Heat transfer:** 

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} = \frac{1}{a} \frac{\partial T}{\partial t}$$

Conservation of energy per unit volume

#### **Assumption:**

the drilling is considered as a one-dimensional process and the laser beam intensity is uniform:

**1-D heat transfer**  

$$\frac{\partial^{2}T}{\partial z^{2}} = \frac{1}{\alpha} \frac{\partial T}{\partial t}$$
Boundary conditions  

$$\frac{-k\left(\frac{dT}{dz}\right)_{z=0}}{as z \to \infty T = T_{0}} = J_{0}$$
Therefy the second second

**REF**: Salonitis, K., A. Stournaras, G. Tsoukantas, P. Stavropoulos and G.Chryssolouris, "A Theoretical and Experimental Investigation on Limitations of Pulsed Laser Drilling", Journal of Materials Processing Technology, (Vol. 183, No. 1, 2007), pp. 96-103.

### **Pulsed Laser Drilling**



**REF**: Salonitis, K., A. Stournaras, G. Tsoukantas, P. Stavropoulos and G.Chryssolouris, "A Theoretical and Experimental Investigation on Limitations of Pulsed Laser Drilling", Journal of Materials Processing Technology, (Vol. 183, No. 1, 2007), pp. 96-103.

### **Pulsed Laser Drilling**



**REF**: Salonitis, K., A. Stournaras, G. Tsoukantas, P. Stavropoulos and G.Chryssolouris, "A Theoretical and Experimental Investigation on Limitations of Pulsed Laser Drilling", Journal of Materials Processing Technology, (Vol. 183, No. 1, 2007), pp. 96-103.

### **Laser Cutting**

Laser cutting has a great number of applications in automotive, aerospace, shipbuilding and material processing industries and it is used for cutting a wide range of materials such as metals, ceramics, and composites regardless of their hardness or electrical conductivity.



Good cutting quality is important, especially if parts are going to be used for assembly.

Statistical design of experiments and analysis can be used to identify the effects of the most important parameters on quality characteristics, such as kerf width, HAZ and cutting edge surface roughness.



**REF**: Stournaras A., P. Stavropoulos, G. Chryssolouris, (2006), "Investigation of Laser Cutting Quality of Aluminium", In the Proceedings of International Congress on Applications of Lasers and Electro-optics, October 30-November 2, Scottsdale, Arizona, USA.

### **Laser Cutting**

Regression analysis has been used for developing empirical models for the combined effect of laser power, cutting speed, pulsing frequency and assist gas pressure on laser cutting quality, i.e. Kerf width, cutting edge surface roughness and squareness.

First and second order main effects as well as interaction effects have been accounted for in the regression model, which has the general form:

$$Y_{j} = a_{0} + a_{1}x_{1} + a_{2}x_{2} + a_{3}x_{3} + a_{4}x_{4} + a_{5}x_{1}^{2} + a_{6}x_{2}^{2} + a_{7}x_{3}^{2} + a_{8}x_{4}^{2} + a_{6}x_{2}^{2} + a_{7}x_{3}^{2} + a_{8}x_{4}^{2} + a_{8$$

 $+a_{9}x_{1}x_{2}+a_{10}x_{1}x_{3}+a_{11}x_{1}x_{4}+a_{12}x_{2}x_{3}+a_{13}x_{2}x_{4}+a_{14}x_{3}x_{4}$ 

where  $Y_{j}$ , j=1,2,3 is the cutting quality parameter ( $Y_1$ : kerf width,  $Y_2$ : surface roughness,  $Y_3$ : squareness),  $x_1$ is the laser power in watt,  $x_2$  is the cutting speed in m/min,  $x_3$  is the pulsing frequency in Hz and  $x_4$  is the assist gas pressure in bar.

Coefficient	Kerf width	Roughness	Squarenes	
a <sub>0</sub>	504.34	106.25	376.99	
a <sub>1</sub>	0.46929	-0.14751	-0.48559	
a <sub>2</sub>	-52.827	8.4864	33.17	
a <sub>3</sub>	-0.029131	0.0018265	8.5473	
a <sub>4</sub>	-102.55	0.85838	-0.0036038	
a <sub>5</sub>	-0.00026054	4.9016e-005	0.0001573	
a <sub>6</sub>	3.1878	0.77448	-2.0805	
a <sub>7</sub>	-1.5565e-006	-9.4349e-009	-0.46552	
a <sub>8</sub>	2.7104	0.043294	5.2871e-007	
a <sub>9</sub>	0.0019046	-0.0058301	-0.0059667	
a <sub>10</sub>	2.3183e-005	1.0137e-007	0.0017512	
a <sub>11</sub>	0.022924	-0.00062169	-3.3974e-006	
a <sub>12</sub>	0.0029872	-9.1454e-005	-0.40466	
a <sub>13</sub>	0.00071328	-0.00014329	3.5441e-005	
a <sub>14</sub>	0	0	0	
R <sup>2</sup>	0.405	0.705	0.78	

#### Regression model coefficients for cutting of Aluminium AA2024

**REF**: Salonitis, K., P. Stavropoulos, Stournaras A., G. Chryssolouris, (2007), "CO<sub>2</sub> Laser Cutting of Aluminium", In the Proceedings of the 5<sup>th</sup> Laser Assisted Netshape Engineering, Erlangen, Germany, (September 2007), pp. 825-835.



### **Laser Cutting**

#### Comparison of regression model results and experimental data for cutting of Aluminium AA2024

REF: Salonitis, K., P. Stavropoulos, Stournaras A., G. Chryssolouris, (2007), "CO<sub>2</sub> Laser Cutting of Aluminium", In the Proceedings of the 5<sup>th</sup> Laser Assisted Netshape Engineering, Erlangen, Germany, (September 2007), pp. 825-835.

### **Remote Welding**

Highly flexible and productive laser welding, used mainly in the automotive industry

The Remote Welding Systems (RWSs) implement:

- High quality, high power laser sources
- Large focal lengths (up to 1.6 m)

- Scanning systems with low inertia deflecting optics (2-mirror or 1-mirror arrangements)





#### **Characteristics:**

- Large Working Volumes (up to 2 m<sup>3</sup>)
- High laser moving speeds (up to 17 m/s)
- High production rates (typically 60 welds/min)
- Inclined welds are realised

**REF**: Tsoukantas G., Salonitis K., Stournaras A., Stavropoulos P. and Chryssolouris G. (2006) "On Optimal Design Limitations of Generalized Two-Mirror Remote Beam Delivery Laser Systems: The case of remote Welding", *The International Journal of Advanced Manufacturing Technology*, DOI: 10.1007/s00170-005-0400-7.

### **Remote Welding Analysis**



**REF**: Tsoukantas G., Salonitis K., Stournaras A., Stavropoulos P. and Chryssolouris G. (2006) "On Optimal Design Limitations of Generalized Two-Mirror Remote Beam Delivery Laser Systems: The case of remote Welding", *The International Journal of Advanced Manufacturing Technology*, DOI: 10.1007/s00170-005-0400-7.

### **Remote Welding Limitations**

Calculating the welding limitations on three different Focal Length options in a large

85

80

75

70

65

60

55

» 10

65

6.3

62



Material	u (m/min)	<i>I<sub>keyhole</sub></i> (10 <sup>4</sup> W/mm²)	Weld Depth at normal incidence (mm)	<i>¢</i> <sub>keyhole</sub> (Degrees)		
				Focal Length 1,000 mm	Focal Length 1,240 mm	Focal Length 1,600 mm
Mild Steel	7.5	2.1	0.8	18	25	42
DC04 (FePO <sub>4</sub> ) Steel	4	2.9	1	25	35	67
Zinc coated 600DP High-strength Steel	2	3.9	1.6	35	50	N/P
Mild Steel 1018	2	1.2	1	14	18	31
AISI 304 Stainless	5	4.0	1.2	37	53	N/P
12SR Stainless	1.3	1.5	2	13	17	29
Aluminium 1100	1	3.1	1	27	38	83
Aluminium 2017	1	2.7	1	24	32	60
Aluminium 2024	7.8	4.7	1	44	68	N/P
Aluminium 7N01	1	2.9	1	26	35	68
Aluminium 5083	1	2.3	1	20	27	47
Aluminium 5182	7.8	4.7	1	44	68	N/P
Aluminium 5000x	5	3.5	1	31	44	N/P
Aluminium 5754	4	2.8	1.5	25	34	64
Aluminium 6000x	5	2.0	1	17	23	40
Aluminium 6016	6	3.7	1	33	47	N/P
Aluminium 6082	7.8	4.7	1	44	68	N/P
Copper	5	5.2	1	51	N/P	N/P
Vanadium	7.5	3.2	1	28	39	N/P

**REF**: Tsoukantas G., Salonitis K., Stournaras A., Stavropoulos P. and Chryssolouris G (2006) "On Optimal Design Limitations of Generalized Two-Mirror Remote Beam Delivery Laser Systems: The case of remote Welding", *The International Journal of Advanced Manufacturing Technology*, DOI: 10.1007/s00170-005-0400-7.

### **Thermal Modelling of Laser Cladding**

**Theoretical Analysis – Laser Power effect** 

Fraction of the supplied powder that contribute to the clad formation

- The mass of the solid particles that reaches the liquid substrate is considered negligible.
- The mass of the liquid particles can be determined from the energy consumed for the melting and the latent heat of fusion from the following equation:

$$\dot{m}_{melted} = \frac{m_{melted}}{t} = \frac{Q_{particles}}{t \cdot L} = \frac{a \cdot Q_L}{t \cdot L} = \frac{a \cdot P}{L}$$

**REF**: Salonitis, K., P. Stavropoulos, A. Stournaras and G. Chryssolouris, "Thermal modelling of laser cladding process", Proceedings of the 5th Laser Assisted Net Shape Engineering, Erlangen, Germany, (September 2007), pp. 303-311

### **Thermal Modelling of Laser Cladding**



□ Increase of the laser power or the increase of the powder feed rate results in higher clad widths

□ Increase of the laser power results in lower clad heights.

□ Average deviation: 15 to 25% depending on the laser power

**REF**: Salonitis, K., P. Stavropoulos, A. Stournaras and G. Chryssolouris, "Thermal modelling of laser cladding process", Proceedings of the 5th Laser Assisted Net Shape Engineering, Erlangen, Germany, (September 2007), pp. 303-311

### **Analytical Modelling of Laser Cladding**



**Estimation of the clad geometry (width, depth, height):** 



**REF**: Lalas C., Tsirbas K., Salonitis K. and Chryssolouris G. (2006) "An analytical model of laser clad geometry", *International Journal of Advanced Manufacturing Technology*, DOI 10.1007/s00170-005-0318-0.

### **Laser Cladding - Experimentation**



**Clad Characteristics** 

Clad geometry includes two main regions, namely the clad and the alloying zone. Clad height (h), width (w) and depth (d) define the final geometry of the clad after the end of the process. In the alloying zone the added material and the molten substrate are mixed. The sum of the alloying zone thickness (a) and the clad depth (d) define the clad dilution (D).



Experimental layout for Laser Cladding

REF: Chryssolouris G., Zannis S., Tsirbas K. and Lalas C. (2002) "An Experimental Investigation of Laser Cladding", CIRP Annals, Vol. 51 No1, pp. 145-148.

### **Basic Laser Cladding Techniques**



**REF:** Chryssolouris G., Zannis S., Tsirbas K. and Lalas C. (2001) "On Laser Cladding", *The 34th CIRP International Seminar on Manufacturing Systems*, 16-18 May 2001, Athens, Greece.

### **Investigation of Pulsed Laser Grooving Process**

- Each pulse results in heating (t<sub>on</sub>) and cooling (t<sub>off</sub>) of the work piece surface.
- Heat transfer within the work piece material:

 $\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial z^2} = \frac{1}{a} \frac{\partial T}{\partial t}$  a: Thermal diffusivity

- Initial & Boundary conditions:

$$\begin{split} & T_{1}(z,x,0) = T_{1-1}^{'} & \text{Heating} \\ & -k \frac{\partial T_{1}}{\partial z} \Big|_{z=0} = Q_{g} \text{ for } -R_{f_{0}} \leq x \leq R_{f_{0}} \\ & h(T_{0} - T')_{Z=0} = -k \frac{\partial T'}{\partial Z} \Big|_{z=0} \text{ for } x \leq -R_{f_{0}} \text{ or } x \geq R_{f_{0}} \\ \hline & T_{1}'(z=0,x,t=0) = T_{1} & \text{Cooling} \\ & h(T_{0} - T')_{Z=0} = -k \frac{\partial T'}{\partial Z} \Big|_{z=0} \end{split}$$



REF: Stournaras A., P. Stavropoulos, G. Chryssolouris, (2006), "Theoretical and Experimental Investigation of Pulsed Laser Grooving Process", In the Proceedings of International Congress on Applications of Lasers and Electro-optics, October 30-November 2, Scottsdale, Arizona, USA.

### **Investigation of Pulsed Laser Grooving Process**

Energy balance of the melt pool:

$$Q_{in} = Q_L + Q_{Cond} + Q_{Conv}$$

 $Q_{in}$ : the energy that enters the work piece  $Q_L$ : the energy required for material's phase change  $Q_{Cond}$ : the heat conducted in the work piece  $Q_{Conv}$ : the heat lost in the air through convection

$$Q_{in} = \int_{x_{1_n}}^{x_{2_n}} Q_g dx \cdot b \cdot t_p$$
$$Q_L = m_i * L = V_i * \rho * L$$

$$Q_{\text{Cond}} = \left(k * A_{\text{Cond}} * \frac{\partial T}{\partial n}\right) * t_p = \left(k * A_{\text{Cond}} * \frac{\Delta T}{\Delta s}\right) * t_p$$

 $Q_{Conv} = (h * A_{Conv} * \Delta T) * t_p$ 

By calculating the volume *Vi* of the melted material at each pulse, the depth *zi* can be calculated

$$Z_{i} = \frac{Q_{in} - k \cdot t_{p} \cdot A_{i} \frac{\Delta T}{\Delta S} - h \cdot A_{i} \cdot t_{p} \cdot \Delta T}{A_{i} \cdot \rho \cdot L + 2 \cdot k \cdot \pi \cdot r_{i} \frac{\Delta T}{\Delta S} \cdot t_{p}}$$

A<sub>i</sub>: Surface area of the melted finite volume r<sub>i</sub>: Radius of the cylindrical finite volume ρ: Density of the material t<sub>p</sub>: Pulse duration

**REF**: Stournaras A., P. Stavropoulos, G. Chryssolouris, (2006), "Theoretical and Experimental Investigation of Pulsed Laser Grooving Process", In the Proceedings of International Congress on Applications of Lasers and Electro-optics, October 30-November 2, Scottsdale, Arizona, USA.

### **Investigation of Pulsed Laser Grooving Process**

#### **Theoretical and Experimental results:**



**REF**: Stournaras A., P. Stavropoulos, G. Chryssolouris, (2006), "Theoretical and Experimental Investigation of Pulsed Laser Grooving Process", In the Proceedings of International Congress on Applications of Lasers and Electro-optics, October 30-November 2, Scottsdale, Arizona, USA.

### **Laser Grooving of Ceramics and Composites**

#### **Experimental Setup**

Laser turning in radial and longitudinal blind cuts Utilization of Off-axial gas jet



#### **Experimental Data**

#### **Ceramic Material: Al<sub>2</sub>O<sub>3</sub>**



#### **Composite Material: Glass/Polyester**



**REF**: Chryssolouris G., Sheng P. and Choi W.C. (1989) "Investigation of the Laser Grooving Process for Ceramic and Composite Materials", *Proc. of the 15th Conference on Production Research and Technology*, NSF, SME, University of California at Berkeley, pp. 617-622.

#### **Laser Process Monitoring**

#### Pulsed Laser Drilling process monitoring using optical and acoustical means

**Process information can be obtained by measuring and characterizing the various forms of energy that propagates from the laser material interaction site.** Electromagnetic radiation and acoustic **waves are two of the most significant signals that can be used for extracting information regarding process' evolution and characteristics.** 



#### **Laser Process Monitoring**

Pulsed Laser Drilling process monitoring using optical and acoustical means



#### Laser Process Monitoring Sensing of Laser Drilling and Grooving/Cutting

**Signal Elaboration** 

#### **Experimental Setup**

Laser

Beam

Gas Jet

Workpiece

x-y Translation Table



#### Utilization of Theoretical Model



#### Closed Loop Control Scheme for Laser Drilling

Microphone



#### Closed Loop Control Scheme for Laser Grooving/Cutting



**REF**: Sheng P. and Chryssolouris G. (1994) "Investigation of acoustic sensing for laser machining processes Part 1: Laser drilling", *Journal of Materials Processing Technology*, Vol. 43, Issues 2-4, pp. 125-144.

Sheng P. and Chryssolouris G. (1994) "Investigation of acoustic sensing for laser machining processes Part 2: Laser grooving and cutting", *Journal of Materials Processing Technology*, Vol. 43, Issues 2-4, pp. 145-163.

### **3D Laser Materials Processing**



The concept of this device allows the entrance of two different Laser beams and their guidance to the moving heads through arms A and B.

By adjusting the angle position of the heads, in combination with the rotating specimen, different geometries can be created.

#### ADJUSTMENT OF SPECIMEN AND ARMS POSITION

**REF**: Chryssolouris G., Sheng P. and Anastasia N. (1991) "Development of Techniques for Three-Dimensional Laser Machining" SAE 1991 Transactions, Vol. 100/Journal of Materials and Manufacturing/Section 5, pp. 916-924.

### **3D Laser Materials Processing**



Incidence Angle

3D LASER MACHINING USING TWO CONVERGING LASER BEAMS

**Incidence Angle** 

This concept utilizes two intersecting beams in order to produce parts with shapes similar to those produced by conventional methods

Turning operations can be accomplished by helix/ring removal [Fig. a, b]

For the case of laser milling, two laser beams are positioned at oblique angles from the workpiece surface to create converging grooves in a workpiece. [Fig. c, d]

REF: Chryssolouris G., Sheng P. and Anastasia N. (1991) "Development of Techniques for Three-Dimensional Laser Machining" *SAE 1991 Transactions*, Vol. 100/Journal of Materials and Manufacturing/Section 5, pp. 916-924.

Tsoukantas G., Salonitis K., Stavropoulos P. and Chryssolouris G. (2002) "An Overview of 3D Laser Materials", *Processing, Proceedings of 3<sup>rd</sup> International Conference on Laser Technologies and Applications*, Patras, Greece, 2002, pp. 224-228.